

Simultaneous Localization and Mapping for Mobile Robots

Introduction and Methods

As mobile robots become more common in general knowledge and practices, as opposed to simply in research labs, there is an increased need for the introduction and methods to Simultaneous Localization and Mapping (SLAM) and its techniques and concepts related to robotics.

Simultaneous Localization and Mapping for Mobile Robots: Introduction and Methods investigates the complexities of the theory of probabilistic localization and mapping of mobile robots as well as providing the most current and concrete developments. This reference source aims to be useful for practitioners, graduate and postgraduate students, and active researchers alike.

Topics Covered:

- Feature Sensors
- Map Sensors
- Mobile Robot Localization
- Non-Holonomic Model
- Probabilistics
- Robotics
- Simultaneous Localization and Mapping (SLAM)



Information Science
REFERENCE

An imprint of IGI Global

INFORMATION SCIENCE REFERENCE
701 E. Chocolate Avenue
Hershey, PA 17033, USA
www.igi-global.com

ISBN 978-1-4666-2109-6



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Simultaneous Localization And Mapping For Mobile Robots Introduction And Methods

PT Brinkman



Simultaneous Localization And Mapping For Mobile Robots Introduction And Methods:

Simultaneous Localization And Mapping For Mobile Robots Introduction And Methods Book Review: Unveiling the Power of Words

In a global driven by information and connectivity, the energy of words has be more evident than ever. They have the capability to inspire, provoke, and ignite change. Such could be the essence of the book **Simultaneous Localization And Mapping For Mobile Robots Introduction And Methods**, a literary masterpiece that delves deep into the significance of words and their effect on our lives. Published by a renowned author, this captivating work takes readers on a transformative journey, unraveling the secrets and potential behind every word. In this review, we will explore the book is key themes, examine its writing style, and analyze its overall impact on readers.

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