



**Symbols**

**Input**

- 1. ego\_i
- 2. map\_i

**Output**

- 1. speed\_act
- 2. throttle\_act
- 3. throttle
- 4. speed
- 5. ego
- 6. map

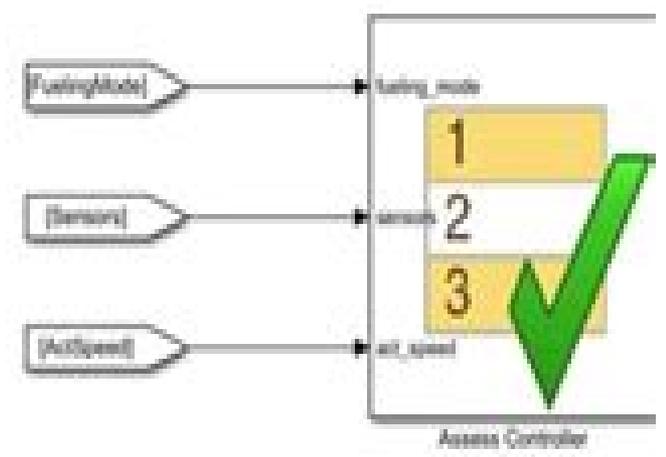
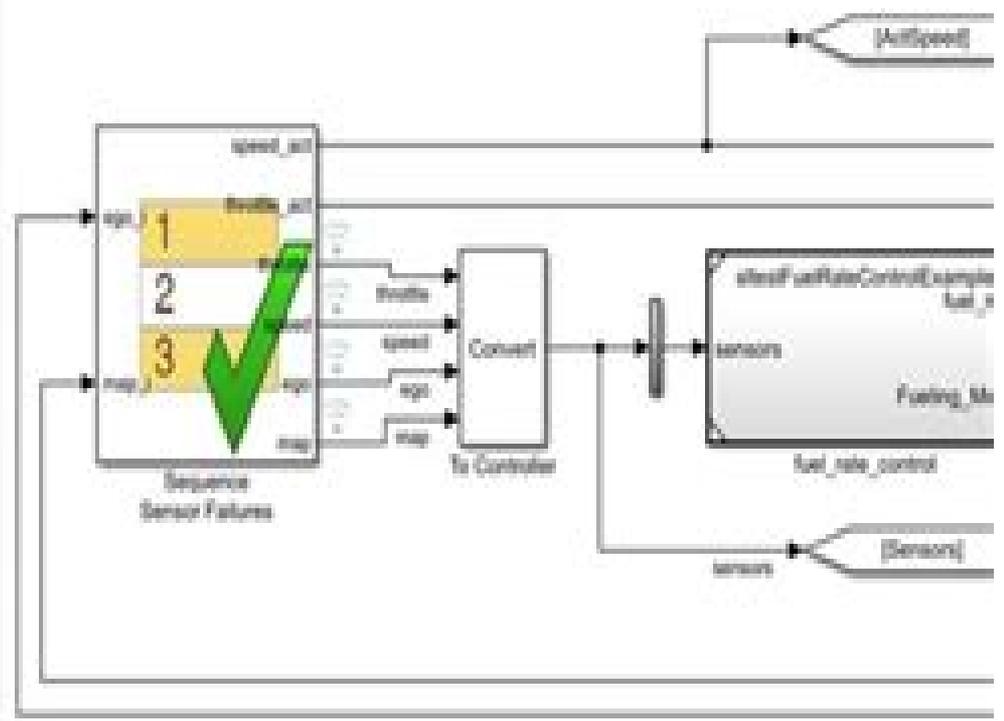
**Local**

**Constant**

**Parameter**

**Data Store Memory**

Step	Transit
<b>Stabilize_Engine</b> throttle = 20; % 0 ==> 20 speed = 300; % 0 ==> 300 ego = ego_i; % 12 ==> 12 map = map_i; % 0 ==> 0 throttle_act = throttle; speed_act = speed;	1. 1
<b>Test_Scenarios</b> throttle = 10; throttle_act = throttle; speed = 400; speed_act = speed; ego = ego_i; map = map_i;	
<b>Test_Overspeed</b> throttle = 30; throttle_act = throttle; speed = 300+ramp(1); speed_act = speed;	1. 2
<b>Reset_to_Normal_Sp</b> throttle = 10;	1. 3



# Embedded Systems Matlab Simulink Solutions

**IM Harris**



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